

Oscilační kriteria pro položárné
diferenciální rovnice neutrálního typu

Brno 28.4.2014

$$\left[r(t) \phi(z'(t)) \right]' + c(t) \phi(x(\sigma(t))) = 0$$

$$z(t) = x(t) + p(t) x(\tau(t))$$

$$\phi(x) = |x|^\alpha \cdot x$$

$$\alpha \geq 1, \quad \sigma(\tau(t)) = \tau(\sigma(t)), \quad \int_0^\infty r^{-1/\alpha}(s) ds = \infty$$

ΣΠΩΝΑΪΒΑCΙ ΜΕΤΟΔΑ (ΒΑCΟΥΛΙΩΝΑ, ΦΖΕΥΡΙΝΑ)

$$[r(t) \phi(z'(t))] + u(t) \phi(x(\sigma(t))) = 0$$

$$\frac{1}{\tau'(t)} [r(\tau(t)) \phi(z'(\tau(t)))] + u(\tau(t)) \phi(x(\sigma(\tau(t)))) = 0$$

$$\begin{aligned} & \frac{p_0 x}{\tau_0} [r(t) \phi(z'(t))] + u(t) \phi(x(\sigma(t))) = 0 \\ & \frac{p_0 x}{\tau_0} [r(\tau(t)) \phi(z'(\tau(t)))] + u(\tau(t)) \phi(p_0 x(\sigma(\tau(t)))) \leq 0 \end{aligned}$$

} (+)

$$y(t) := r(t) z'(t) + \frac{p_0 x}{\tau_0} r(\tau(t)) \phi(z'(\tau(t)))$$

$$y(t) + \min \{u(t), u(\tau(t))\} [\phi(x(\sigma(t))) + \phi(p_0 x(\sigma(\tau(t))))] \leq 0$$

ΣΠΩΝΑΪΑCΙ ΜΕΤΟΔΑ (ΒΑΡΕΛΙΩΝΑ, ΖΕΥΡΙΝΑ)

$$y'(t) = r(t)z'(t) + \frac{T_0^\alpha}{\Gamma_0} r(\tau(t)) \phi(z'(\tau(t)))$$

$$y'(t) + \min\{c(t), c(\tau(t))\} \left[\phi(x(r(t))) + \phi(p_0 x(\tau(\tau(t)))) \right] \leq 0$$

↗ $\delta_0 \tau = \tau_0 \delta$

$$y'(t) + \min\{c(t), c(\tau(t))\} 2^{1-\alpha} \phi(z(\tau(t))) \leq 0$$

$$y'(t) + \min\{c(t), c(\tau(t))\} 2^{1-\alpha} \left[\int_{t_0}^{t(t)} r^{-1/\alpha}(\tau) d\tau \right]^\alpha \frac{T_0}{\Gamma_0 + T_0} y(\tau^{-1}(\tau(t))) \leq 0$$

METODA RICCATIHO BOUNCE

$$(*) \quad \boxed{x'' + c(t)x = 0} \quad w = \frac{x'}{x} \quad \boxed{w' + c(t) + w^2 = 0}$$

$$\rho > 0, \quad w > 0 \quad (\text{je-li } c > 0 \text{ a } x > 0)$$

$$(\rho w)' + \rho w^2 + \rho c - \rho' w = 0$$

$$(\rho w)' + \rho \left(w - \frac{\rho'}{2\rho} \right)^2 + \rho c - \frac{(\rho')^2}{4\rho} \leq 0$$

$$\rho(t)w(t) - \rho(t_1)w(t_1) + \int_{t_1}^t \rho(s)c(s) - \frac{[\rho'(s)]^2}{4\rho(s)} ds \leq 0$$

$$\int_0^{\infty} \rho(s)c(s) - \frac{(\rho'(s))^2}{4\rho(s)} ds = \infty \Rightarrow (*) \text{ o.s.c.}$$

Рискованная методика по $[r\phi(z')]^1 + c\phi(x_0) = 0$, $z = x + p \cdot x_0$

$$\omega(t) = \rho(t) \frac{r(t)\phi(z'(t))}{\phi(z(\delta(t)))}$$

$$\omega'(t) = \frac{\rho'(t)}{\rho(t)} \omega(t) + \rho(t) \frac{[r(t)\phi(z'(t))]'}{\phi(z(\delta(t)))} - \alpha \rho(t) \frac{r(t)\phi(z'(t))}{\phi(z(\delta(t)))} \frac{\delta'(t) z'(\delta(t))}{z(\delta(t))}$$

$$\left. \begin{array}{l} \delta(t) \leq t \\ r(t)\phi(z'(t)) \text{ убывает} \end{array} \right\} z'(\delta(t)) \geq \left[\frac{r(t)}{r(\delta(t))} \right]^{1/\alpha} z'(t)$$

$$\omega'(t) \leq \frac{\rho'(t)}{\rho(t)} \omega(t) + \rho(t) \frac{[r(t)\phi(z'(t))]'}{\phi(z(\delta(t)))} - \frac{\alpha \delta'(t)}{\rho^{1/\alpha}(t) r^{1/\alpha}(t)} |\omega(t)|^{\frac{\alpha+1}{\alpha}}$$

ΡΙΣΤΟΛΗ ΜΕΤΟΔΑ ΤΩΣ $[r\phi(z')] + c\phi(x\alpha) = 0$, $z = x + p \cdot x\alpha\tau$

$$\omega(t) = \rho(t) \frac{r(t)\phi(z'(t))}{\phi(z(\alpha(t)))}$$

$$\omega'(t) \leq \frac{\rho'(t)}{\rho(t)} \omega(t) + \rho(t) \frac{[r(t)\phi(z'(t))]'}{\phi(z(\alpha(t)))} - \frac{\alpha \alpha'(t)}{\rho^{1/\alpha}(t) r^{1/\alpha}(t)} |\omega(t)|^{\frac{\alpha+1}{\alpha}}$$

$$\nu(t) = \rho(t) \frac{r(\tau(t))\phi(z'(\tau(t)))}{\phi(z(\alpha(t)))}$$

$$\nu'(t) \leq \frac{\rho'(t)}{\rho(t)} \nu(t) + \rho(t) \frac{[r(\tau(t))\phi(z'(\tau(t)))]'}{\phi(z(\alpha(t)))} - \frac{\alpha \alpha'(t)}{\rho^{1/\alpha}(t) r^{1/\alpha}(t)} |\nu(t)|^{\frac{\alpha+1}{\alpha}}$$

INOVACE KLASICKÉHO POSTUPU

PRŮVODNÍ

F+M (2014)

1) Součet rovnice

\Rightarrow vložte lim. konstante

$$2) \left(\frac{1}{2}x + \frac{1}{2}y \right)^\alpha \leq \frac{1}{2}x^\alpha + \frac{1}{2}y^\alpha$$

$$\Rightarrow \left(\frac{1}{2}x + \frac{1}{2}y \right)^\alpha \leq \frac{1}{2}x^\alpha + \frac{1}{2}y^\alpha$$

$$3) \min \{ c(t), c(\tau(t)) \}$$

$$\Rightarrow \min \{ c(t), \varphi \cdot c(\tau(t)) \}$$

$$4) c(\tau(t)) = \tau(c(t))$$

$$\Rightarrow c(\tau(t)) \geq \tau(c(t)), \text{ pokud } x \text{ roste}$$

Věta: Jestliže existuje $l > 1$ a $\varphi > 0$ taková, že

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t p(s) \min \{c(s), \varphi c(\tau(s))\} - \frac{1}{(\alpha+1)^{\alpha+1}} \frac{p(s) r(s)}{[d'(s)]^\alpha}$$

$$\cdot \left[l^{\alpha-1} + (l^*)^{\alpha-1} \frac{P_0 \varphi}{T_0} \right] \left[\frac{p_+(s)}{p(s)} \right]^\alpha ds = \infty,$$

pobom rovnice

$$\left[r(s) \phi(z'(s)) \right]' + c(s) \phi(x(s)) = 0, \quad z(s) = x(s) + p(s) x(\tau(s))$$

osciluje.

- Poznámky:
- 1) φ : $c(s) = \varphi \cdot c(\tau(s))$
 - 2) p : druhý člen + lineár $p \in \int 1/s ds$
 - 3) l : $[e^{\alpha} \dots e^{\alpha}] \rightarrow \min$

POZOVNÁNI METOD

ZOBECNĚNÁ NEUTRÁLNÍ EULEROVA ROVNICE

$$\left[\phi(z'(t)) \right]' + \frac{\beta}{t^{\alpha+1}} \phi(x(\lambda_2 t)) = 0$$

$$z(t) = x(t) + p_0 x(\lambda_1 t), \quad 0 < \lambda_2 < \lambda_1 < 1$$

$$\phi(x) = |x|^{\alpha-1} x, \quad \alpha \geq 1$$



