### Riccati differential equation and it's generalizations

A real treasure in oscillation and comparison theory of second order linear and half-linear differential equations

#### Robert Mařík

Mendel University in Brno Czech Republic

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#### **REAL STORY**

A talk with the man at a copy center where I ordered to make hardcopies of my master thesis.



#### THE AIM OF THE TALK

The aim of the talk is to convince the audience that the worker from the copy center was wrong.







## Second order linear differential equation

• Riccati equation method for second order linear ODE • Important pairs of points

- Zero interlacing theorem Sturm majorant theorem Oscillation criteria
	- Principal solutions



Riccati equation method for second order linear ODE

$$
w = x'/x
$$
  

$$
w = x'/x
$$
  

$$
w' + c(t) + w2 = 0
$$
  

$$
x = \exp(\int w) \qquad w' + c(t) + w2 = 0
$$

#### Important pairs of points





#### Zero interlacing theorem

The following cannot occur due to unique solvability of IVP for Riccati equation

- $x_1$ ,  $x_2$  solutions of the same equation
- $x_1 > 0$  on  $(a, b)$ ,  $x(a) = 0 = x(b)$
- $x_2 > 0$  on [a, b]



#### STURM MAJORANT THEOREM

The following cannot occur due to comparison theorem for first order differential inequalities

- $x_1$  solution of  $x'' + c(t)x = 0$
- $x_1 > 0$  on  $(a, b)$ ,  $x(a) = 0 = x(b)$
- $x_2$  solution of  $x'' + C(t)x = 0$ ,  $C(t) > c(t)$
- $x_2 > 0$  on [a, b]





 $x'' + c(t)x = 0$ 

- Oscillatory if some solution (and thus all solutions) have zeros in every neighborhood of  $\infty$ .
- Nonoscillatory otherwise (there exists a solution positive in some neighborhood of  $\infty$ ).

(Non-)oscillation in terms of Riccati equation

$$
x'' + c(t)x = 0 \qquad \qquad w' + c(t) + w^2 = 0
$$

• equation is nonoscillatory • **•** equation has solution on  $[T, \infty)$  for large *T* 

• equation is oscillatory **•** equation has no solution on  $[T, \infty)$ , no matter how large *T* is



Oscillation of

$$
x'' + c(t)x = 0
$$

is ensured if  $c(t)$  is large enough. For example in one of the following sense

pointwise criteria simplest possibility, from comparison with suitable equation,

e.g.: 
$$
x'' + kt^{-2}x = 0
$$
 is nonoscillatory iff  $k \le \frac{1}{4}$   
\n $x'' + c(t)x = 0$  is oscillatory if  $c(t) \ge \left(\frac{1}{4} + \varepsilon\right)t^{-2}$  for large  $t$   
\nand nonoscillatory if  $c(t) \le \frac{1}{4}t^{-2}$  for large  $t$ 

integral criteria can be used if  $c(t)$  is not large enough for every  $t$  but its mean value is large e.g.:  $\int_0^\infty c(t) dt = \infty$  is sufficient for oscillation

series of conjugacy criteria can be used if the mean value of  $c(t)$  is small, but there is a series of subintervals where  $c(t)$  is large enough to bend every solution to zero. Certain lower bound for mean value of *c*(*t*) is required if we wish to eliminate this possibility how the equation can be turned to oscillation, e.g. in nonoscillation criteria.



$$
x'' + c(t)x = 0
$$

**Leighton, Morse:** Let *u* and *v* be nontrivial solutions of nonoscillatory equation. The following conditions are equivalent and each can be used to determine principal solution *u* (unique up to a constant multiple) and nonprincipal solution *v* (linearly independent on principal solution).

\n- \n
$$
\lim_{t \to \infty} \frac{u(t)}{v(t)} = 0
$$
\n
\n- \n
$$
\frac{u'(t)}{u(t)} < \frac{v'(t)}{v(t)}
$$
\n in a neighborhood of  $\infty$ \n
\n- \n
$$
\int_{-\infty}^{\infty} \frac{1}{u^2(t)} \, dt = \infty, \int_{-\infty}^{\infty} \frac{1}{v^2(t)} \, dt < \infty
$$
\n
\n



## Half-linear ODE

• Half-linear ODE • Generalized Riccati equation • Use of linear transformation theory • Linear transformation theory in the terms of Riccati equation • Half-linear substitute for missing transformation theory • Modified Riccati equation • Available estimates for *H* function • Theorem samples (principal solution) • Theorem samples (perturbed Euler equation) • Theorem samples (Nehari-type nonoscillation criterion)



#### Half-linear ODE

$$
(\mathbf{r}(t)\Phi(\mathbf{x}'))' + c(t)\Phi(\mathbf{x}) = 0,
$$
 (\*)

where

$$
\Phi_p(x) = |x|^{p-2}x, \quad p > 1
$$

and if the subscript is missing, we assume it to be p, i.e.  $\Phi(x) := \Phi_p(x)$ .

Equation (\*) has been introduced in 70's by Mirzov and Elbert. Equation (\*) and related equations have been later studied by many authors (including Došlá, Došlý, Drábek, Fišnarová, Hasil, Hata, Jaroš, Kong, Kusano, Li, Lomtatidze, Manojlovič, Marić, Marini, Matsumura, Matucci, Naito, Ogata, Onitsuka, Řehák, Sugie, Sun, Tanigawa, Veselý, Wang, Usami, Xu, Yamaoka, Yoshida)

#### GENERALIZED RICCATI EQUATION

$$
(r(t)\Phi(x'))' + c(t)\Phi(x) = 0
$$
\n
$$
w = r\Phi(x'/x)
$$
\n
$$
w' + c(t) + (p-1)r^{1-q}(t)|w|^q = 0
$$
\n
$$
q = \frac{p}{p-1}
$$

(i.e. essentially the same as in the linear case)

USE OF LINEAR TRANSFORMATION THEORY

Kneser: 
$$
x'' + c(t)x = 0
$$
 
$$
\begin{cases} c(t) = \frac{1}{4t^2} \text{ is critical case} \\ \text{oscillatory if } \liminf_{t \to \infty} t^2 c(t) > \frac{1}{4} \\ \text{nonoscillatory if } \limsup_{t \to \infty} t^2 c(t) < \frac{1}{4} \end{cases}
$$

Refinement (e.g. Hartman's book):

$$
(ty')' + td(t)y = 0
$$
\n
$$
s = \ln(t), y(s) = x(t)
$$
\n
$$
y'' + \left[\frac{1}{4t^2} + d(t)\right]x = 0
$$
\n
$$
x'' + \left[\frac{1}{4t^2} + d(t)\right]x = 0
$$
\n
$$
x'' + \left[\frac{1}{4t^2} + d(t)\right]x = 0
$$

Critical case:  $t^2 d(t) = \frac{1}{4\pi}$  $\frac{1}{4s^2} \iff d(t) = \frac{1}{4t^2 \ln^2 t}$ 

$$
x'' + \left[\frac{1}{4t^2} + d(t)\right]x = 0
$$
\n
$$
\begin{cases}\n\text{oscillatory if } \liminf_{t \to \infty} t^2 \ln^2(t) d(t) > \frac{1}{4} \\
\text{nonoscillatory if } \limsup_{t \to \infty} t^2 \ln^2(t) d(t) < \frac{1}{4} \\
d(t) = \frac{1}{4t^2 \ln^2(t)} \text{ is critical case} \implies \text{another transformation} \dots\n\end{cases}
$$

This approach does not have known extension to halflinear ODE's (lack of transformation formula).

#### LINEAR TRANSFORMATION THEORY IN THE TERMS OF RICCATI EQUATION

We use two different languages to describe one thing (dependent variable transformation).

$$
L[x] := (r(t)x')' + c(t)x = 0
$$
\n
$$
w = r\frac{x'}{x}
$$
\n
$$
w' + c(t) + r^{-1}(t)w^2 = 0
$$
\n
$$
x(t) = h(t)y(t)
$$
\n
$$
v = h^2(w - w_h), w_h = r\frac{h'}{h}
$$
\n
$$
R(t)y' + C(t)y = 0
$$
\n
$$
R(t) = r(t)h^2(t)
$$
\n
$$
x = h(t)y \implies \frac{x'}{x} = \frac{h'}{h} + \frac{y'}{y} \implies rh^2\frac{y'}{y} = h^2(r\frac{x'}{x} - r\frac{h'}{h}) \implies R\frac{y'}{y} = h^2(r\frac{x'}{x} - r\frac{h'}{h})
$$

$$
w = r\Phi(x'/x)
$$
  
\n
$$
w' + c(t) + (p-1)r^{1-q}(t)|w|^q = 0
$$
  
\n
$$
L[x] := (r(t)\Phi(x'))' + c(t)\Phi(x) = 0
$$
  
\n
$$
v = h^p(w - w_h)
$$
  
\n
$$
w_h = r\Phi(h'/h)
$$
  
\n
$$
v' + h(t)L[h](t) + (p-1)Q(t)H(v/G) = 0
$$

$$
Q(t) = r(t)|h'(t)|^p
$$
  
\n
$$
H(v) = |v+1|^q - qv - 1 = q\left(\frac{|v+1|^q}{q} - (v+1) + \frac{1}{p}\right) \ge 0, G(t) = r(t)h(t)\Phi(h'(t))
$$

(note slightly different notation than usually found in papers)

#### MODIFIED RICCATI EQUATION

$$
w = r\Phi(x'/x)
$$
\n
$$
w' + c(t) + (p - 1)r^{1-q}(t)|w|^{q} = 0
$$
\n
$$
L[x] := (r(t)\Phi(x'))' + c(t)\Phi(x) = 0
$$
\n
$$
w' + c(t) + (p - 1)r^{1-q}(t)|w|^{q} = 0
$$
\n
$$
Q(t) = r(t)|h'(t)|^{p}
$$
\n
$$
H(v) = |v + 1|^{q} - qv - 1
$$
\n
$$
G = rh\Phi(h')
$$
\nModified Riccati equation:

\n
$$
v' + h(t)L[h](t) + (p - 1)Q(t)H(v/G) = 0
$$
\n
$$
L_{\alpha}[x] := (r_{\alpha}(t)\Phi_{\alpha}(x'))' + c_{\alpha}(t)\Phi_{\alpha}(x) = 0
$$
\n
$$
v' + c_{\alpha}(t) + (\alpha - 1)r_{\alpha}^{1-\beta}(t)|v|^{\beta} \le 0
$$
\nclassical methods

Existence of positive solution of  $L[x] = 0$  implies existence of positive solution  $L_{\alpha}[x] = 0$ .



#### Available estimates for *H* function

$$
H(v) = |v+1|^q - qv - 1 = q\left(\frac{|v+1|^q}{q} - (v+1) + \frac{1}{p}\right) \ge 0
$$
  

$$
H(v) \approx \frac{q(q-1)}{2}v^2
$$
 for small v, 
$$
H(v) \approx |v|^q
$$
 for large v



#### Global estimates

• 
$$
H(v) \le \frac{q}{2}v^2
$$
 (for  $p \le 2$ )  
\n•  $H(v) \ge \frac{q}{2}v^2$  (for  $p \ge 2$ )  
\n•  $H(v) \ge \frac{q}{2}v^2$  (for  $p \ge 2$ )

 $\bullet$  *H*(*v*) ≤ *βv*<sup>α</sup> (for *p* ≤ 2, *α* ∈ [2, *q*], suitable *β*, missing sharp effective formula for *β*)

 $\bullet$  *H*(*v*) ≥ *βv*<sup>α</sup> (for *p* ≥ 2, *α* ∈ [*q*, 2], suitable *β*, missing sharp effective formula for *β*)

• 
$$
\frac{|t|^{\beta}}{\beta} - t + \frac{1}{\alpha} \le \frac{|t|^q}{q} - t + \frac{1}{p}
$$
 (if  $\beta \le q$ )

#### Local estimates

•  $K_1 v^2 \leq H(v) \leq K_2 v^2$ (for suitable  $K_1$ ,  $K_2$  and on compact interval)

• 
$$
H(v) = \frac{q(q-1)}{2}v^2(1+o(1))
$$
 (as  $v \to 0$ )

• 
$$
\frac{|t|^{\beta}}{\beta} - t + \frac{1}{\alpha} \le \frac{\beta - 1}{q - 1} \left[ \frac{|t|^q}{q} - t + \frac{1}{p} \right]
$$
 (if either  $\beta \le q$  and  $t \ge 1$  or  $\beta \ge q$  and  $t \in (1 - \varepsilon, 1]$ )



Došlý and Elbert via global quadratic estimate of *H*:

$$
p \ge 2: \quad u \text{ is principal} \implies \int^{\infty} \frac{1}{r(t)u^2(t)|u'(t)|^{p-2}} dt = \infty
$$
\n
$$
p \in (1,2]: \quad \int^{\infty} \frac{1}{r(t)u^2(t)|u'(t)|^{p-2}} dt = \infty \implies u \text{ is principal}
$$

#### Fišnarová and Mařík via global power-like estimate of *H*:

The integral 
$$
\int^{\infty} \frac{1}{r(t)u^2(t)|u'(t)|^{p-2}} dt
$$
 can be replaced by
$$
I_{\alpha} := \int^{\infty} \frac{dt}{r^{\alpha-1}(t)u^{\alpha}(t)|u'(t)|^{(p-1)(\alpha-q)}}
$$

where  $\alpha \in [q, 2]$  if  $p \ge 2$  and  $\alpha \in [2, q]$  if  $p \le 2$ . (q is a conjugate number to p)

,

**Example:** The latter condition (F-M) allows to detect  $u(t) = 1 - 1/t^9$  as principal solution of

$$
(\Phi(x'))' + \frac{15t^{-3/2}}{(t^9 - 1)^{1/2}} \Phi(x) = 0, \quad p = 3/2, \quad t > 1,
$$

the former (D-E) fails.



#### THEOREM SAMPLES (PERTURBED EULER EQUATION)

Došlý, Fišnarová, Mařík (J. Math. Anal. Appl. 2013): Let *h*(*t*) > 0, *h* 0 (*t*) > 0,  $h(t)L_p(h)(t) \geq 0$  and either

$$
\limsup_{t\to\infty} r(t)h(t)\Phi(h'(t)) < \infty \text{ and } \int_0^\infty r^{1-q}(t)h^{-q}(t) dt = \infty
$$

or

$$
\lim_{t \to \infty} r(t)h(t)\Phi(h'(t)) = \infty \text{ and } \int_{0}^{\infty} r^{-1}(t)h^{-2}(t)h'^{2-p}(t) dt = \infty.
$$

Denote

$$
a(t) = \left(\frac{q}{\beta}\right)^{1-\alpha} r(t)h^{\alpha-q(\alpha-1)}(t)|h'(t)|^{-\alpha+p}, b(t) = h^{q(1-\alpha)}(t)\left[\left(\frac{q}{\beta}-1\right)r(t)h'^p(t) + c(t)h^p(t)\right]
$$

If  $\alpha > p$  and  $L_p[x] = 0$  is nonoscillatory, then  $(\Phi_\alpha(a(t)x'))' + b(t)\Phi_\alpha(x) = 0$  is also nonoscillatory.

Sugie and Yamaoka (Acta Math. Hungar. 2006) – a special case of the previous result: If  $\alpha > p$  and

$$
(\Phi_p(x'))' + t^{-p} \left[ \left( \frac{p-1}{p} \right)^p + \left( \frac{p-1}{p} \right)^{p-1} \delta(t) \right] \Phi_p(x) = 0
$$

is nonoscillatory, then

$$
(\Phi_{\alpha}(x'))' + t^{-\alpha} \left[ \left( \frac{\alpha - 1}{\alpha} \right)^{\alpha} + \left( \frac{\alpha - 1}{\alpha} \right)^{\alpha - 1} \delta(t) \right] \Phi_{\alpha}(x) = 0
$$

is also nonoscillatory.



Theorem samples (Nehari-type nonoscillation criterion)

<span id="page-19-0"></span>
$$
L[x] := (r(t)\Phi(x'))' + c(t)\Phi(x) = 0 \qquad \text{(under examination)}
$$
  

$$
\widetilde{L}[x] := (r(t)\Phi(x'))' + \widetilde{c}(t)\Phi(x) = 0 \qquad \text{(nonoscillatory)}
$$

**Došlý (J. Math. Anal. Appl. 2006):** Let 
$$
h \in C^1
$$
 be a positive function such that  $h'(t) > 0$   
for large  $t$ , say  $t > T$ . Denote  $G(t) := \int_T^t \frac{ds}{r(s)h^2(s)(h'(s))^{p-2}}$  and suppose that  

$$
\lim_{t \to \infty} G(t)r(t)h(t)\Phi(h'(t)) = \infty, \qquad \text{and} \quad \lim_{t \to \infty} G^2r(t)h^3(t)(h'(t))^{p-2}\widetilde{L}[h](t) = 0.
$$
If 
$$
\int_{t \to \infty}^{\infty} [c(t) - \widetilde{c}(t)]h^p(t) dt < \infty
$$
 and  

$$
\limsup_{t \to \infty} \int_T^t \frac{ds}{r(s)h^2(s)(h'(s))^{p-2}} \int_t^{\infty} (c(s) - \widetilde{c}(s))h^p(s) ds < \frac{1}{2q},
$$

$$
\liminf_{t \to \infty} \int_T^t \frac{ds}{r(s)h^2(s)(h'(s))^{p-2}} \int_t^{\infty} (c(s) - \widetilde{c}(s))h^p(s) ds > -\frac{3}{2q},
$$

then [\(\\*\)](#page-19-0) is nonoscillatory.



Special cases of this theorem produce efficient and sharp oscillation criteria. The result of the effort to improve further the constants on right-hand sides will be presented (among others) in the talk at RIMS Kyoto, Nov 4, 2014.

## Half-linear PDE

- Elliptic half-linear PDE Generalized Riccati equation Concept of oscillation • Known result – detection of oscillation from ODE
- Observation and curious question  $1/2$  Answer  $1/2$  nonradial oscillation criteria
- Known result linear oscillation criterion Observation and curious question 2/2
	- Answer  $2/2$  sublinear versus general



$$
\operatorname{div}\left(A(x)||\nabla u||^{p-2}\nabla u\right)+c(x)|u|^{p-2}u=0\tag{*}
$$

 $A(x)$  is either scalar function or elliptic matrix with maximal and minimal eigenvalues  $\lambda_{\text{max}}(x)$ and  $\lambda_{\min}(x)$ .

Alegretto, delPino, Drábek, Jaroš, Kusano, Mawhin, Naito, Usami, Xu, Yohsida

GENERALIZED RICCATI EQUATION

$$
\text{matrix function } A\n\begin{array}{c}\n\text{div}\left(A(x)||\nabla u||^{p-2}\nabla u\right) + c(x)|u|^{p-2}u = 0 \\
\text{matrix function } A\n\end{array}\n\text{scalar function } A\n\begin{array}{c}\n\text{scalar function } A \\
\text{div } w + c(x) + (p-1)\cdots \le 0\n\end{array}\n\text{value: } \text{div } w + c(x) + (p-1)A^{1-q}(x)||w||^q = 0
$$

- Can be used to derive oscillation criteria (the inequality if  $A$  is a matrix does not matter)
- We (almost) miss nonoscillation criteria from the solvability of Riccati equation we cannot (without additional assumptions) deduce, that (\*) has a positive solution.

#### Concept of oscillation

Eq. (\*) is said to be *oscillatory* if it possesses no solution  $u(x)$  which is positive for large  $||x||$ .



Došlý (2001): Equation

$$
\operatorname{div}(\|\nabla u\|^{p-2}\nabla u)+c(x)|u|^{p-2}u=0
$$

is oscillatory, if the ordinary differential equation

$$
\left(r^{n-1}|u'|^{p-2}u'\right)' + r^{n-1}\left(\frac{1}{\omega_n r^{n-1}}\int_{\{|x||=r} c(x) d\sigma\right)|u|^{p-2}u = 0
$$
\n(\*)

is oscillatory. The number  $\omega_n$  is the surface area of the unit sphere in  $\mathbb{R}^n$ .

- Usami (1998) proved essentialy equivalent version of this theorem formulating the conclusion in terms of associated Riccati equation rather than half-linear ODE (\*).
- **Jaroš, Kusano and Yoshida (2000)** proved independently similar result (for  $A(x) =$  $a(||x||)$ *I* and differentiable  $a(\cdot)$ ).

#### Observation and curious question 1/2

Oscillation criteria depend in fact on the mean value of  $c(x)$  over spheres centered in the origin. Is it possible to detect oscillation of

$$
\mathsf{div}\Big(\bm A(\bm x)\|\nabla u\|^{p-2}\nabla u\Big)+c(\bm x)|u|^{p-2}u=0
$$

in such an extreme case as

$$
\int_{||x||=r} \mathbf{c}(\mathbf{x}) \, \mathrm{d}\sigma = 0?
$$



#### ANSWER  $1/2$  – nonradial oscillation criteria

Let  $\Omega$  be unbounded simply connected domain in  $\mathbb{R}^n$ , with smooth boundary  $\partial\Omega$ . Let  $k \in (1,\infty)$  real number and  $\alpha$  be nonnegative smooth function satisfying

(i) 
$$
\alpha(x) = 0
$$
 iff  $x \notin \Omega$ ,  
\n(ii)  $\int_{1}^{\infty} \left( \int_{\substack{|x||=t \\ x \in \Omega}} \alpha(x) d\sigma \right)^{1-q} dt = \infty$ .  
\nIf  
\n
$$
\lim_{t \to \infty} \int_{\substack{1 \leq ||x|| \leq t \\ x \in \Omega}} \alpha(x) \left( c(x) - \frac{k}{(p\alpha(x))^p} ||\nabla \alpha(x)||^p \right) dx = \infty,
$$
\nthen the equation  
\n
$$
\alpha(x) = 0
$$

$$
\mathsf{div}\left(\|\nabla u\|^{p-2}\nabla u\right)+c(x)|u|^{p-2}u=0
$$

is oscillatory.

(Assuming that the integrals are well defined.)



For  $n = 2$  consider the equation

$$
\Delta u + c(x)u = 0
$$
 (\*)

If

$$
\lim_{t\to\infty}\frac{1}{\ln t}\int_1^t r\int_0^\pi c(r,\varphi)\sin^2(\varphi)\,d\varphi\,dr>\frac{\pi}{2},
$$
 (\*)

where  $c(r, \varphi)$  is  $c(x)$  in polar coordinates, then  $(*)$  is oscillatory.

**Example.** The potential 
$$
c(r, \varphi) = \frac{A}{r^2} \sin \varphi
$$
 satisfies

$$
\int_0^{2\pi} \sin \varphi \, d\varphi = 0 \quad \text{and} \quad \int_0^{\pi} \sin^3 \varphi \, d\varphi = \frac{4}{3} > 0
$$

Thus the oscillation of (\*) cannot be detected by any criterion based on the mean value of *c* over the whole sphere centered in the origin, but the oscillation is guaranteed by (\*\*) for sufficiently large *A*.



**Xu (2006):** Let 
$$
\theta \in C^1([r_0, \infty], \mathbb{R}^+)
$$
,  $m > 1$ ,  $\lambda \in C([r_0, \infty), \mathbb{R}^+)$ . If  
\n
$$
\lim_{r \to \infty} \int_{r_0 \leq ||x|| \leq r} \left[ \theta(||x||) c(x) - \lambda(||x||) \frac{m}{4} \frac{\theta'^2(||x||)}{\theta(||x||)} \right] dx = \infty
$$

and

$$
\lim_{r \to \infty} \int_{r_0 \leq ||x|| \leq r} \frac{1}{\theta(||x||) \lambda(||x||)} dx = \infty, \quad \text{where } \lambda(r) \geq \max_{||x|| = r} \lambda_{\max}(x)
$$

 $\displaystyle {\rm then} \left(\right. A(x)\nabla u \right) + c(x)u = 0 \quad \text{is oscillatory}.$ 

### Observation and curious question 2/2

The oscillation is ensured if  $c(x)$  is large enough and  $A(x)$  small enough. The measure of this "smallness" in the linear case is  $\lambda_{\text{max}}$ . There is a bunch of similar half-linear oscilation theorems, where the measure for the "smallness" of *A* is  $\frac{\lambda_{\text{max}}^p}{n-1}$  $\lambda_{\min}^{p-1}$ min . Why such a discrepancy appears? (Note that  $\lambda_{\text{max}} \leq \frac{\lambda_{\text{max}}^p}{\lambda_{\text{max}}^p}$ *p*  $\lambda_{\min}^{\text{P-1}}$  and thus the half-linear approach is worse than linear even in the case when  $p = 2!)$ 

### . ANSWER  $2/2$  – sublinear versus general

Let

$$
b(r) = \int_{\vert\vert x\vert\vert=r} c(x) d\sigma,
$$

and either

$$
1 < p \le 2 \quad \text{and} \quad a(r) = \int_{\|x\| = r} \lambda_{\max}(x) \, \mathrm{d}\sigma
$$

or

$$
1 < p \quad \text{and} \quad a(r) = \int_{\vert\vert x\vert\vert=r} \lambda_{\max}^p(x) \lambda_{\min}^{1-p}(x) \, \mathrm{d}\sigma.
$$

If

$$
(a(r)\Phi(u'))' + b(r)\Phi(u) = 0
$$

is oscillatory, then

$$
\operatorname{div}\Big(A(x)\|\nabla u\|^{p-2}\nabla u\Big)+c(x)|u|^{p-2}u=0.
$$

is also oscillatory.



$$
w(x) = A(x) \frac{\|\nabla u(x)\|^{p-2} \nabla u(x)}{|u(x)|^{p-2} u(x)}, \qquad \|w\| \le \lambda_{\max} \frac{\|\nabla u\|^{p-1}}{|u|^{p-1}}
$$
  
\n
$$
p > 1 \text{ arbitrary:}
$$
  
\n
$$
\text{div } w + c + (p - 1) \frac{\langle A \|\nabla u\|^{p-2} \nabla u, \nabla u\rangle}{|u|^p} = 0
$$
  
\n
$$
\text{div } w + c + (p - 1) \lambda_{\min} \frac{\|\nabla u\|^{p}}{|u|^p} \le 0
$$
  
\n
$$
\frac{\|\nabla u\|^{p}}{|u|^p} \ge \frac{\|w\|^{q}}{\lambda_{\max}^{q}}
$$
  
\n
$$
\text{div } w + c + (p - 1) \lambda_{\min} \frac{\|\nabla u\|^{p}}{|u|^p} \le 0
$$
  
\n
$$
\frac{\|\nabla u\|^{2-p}}{|u|^{2-p}} \ge \frac{\|w\|^{2-p}}{\lambda_{\max}^{(2-p)/(p-1)}}
$$
  
\n
$$
\text{div } w + c + (p - 1) \lambda_{\min} \frac{1}{\lambda_{\max}^{q}} \|w\|^{q} \le 0
$$
  
\n
$$
\text{div } w + c + (p - 1) \lambda_{\min} \frac{1}{\lambda_{\max}^{q}} \|w\|^{q} \le 0
$$

**Explanation of the difference:** The inequality for  $\Vert w \Vert$  is powered to  $(2-p)/(p-1)$  if  $p \in (1,2]$ , which is not possible if  $p > 2$ . If  $p > 2$ , then  $\|w\|$  is powered to  $q > (2 - p)/(p - 1)$ .



Part 4

# Summary





Conclusion: Riccati equation provides tool for simple proof of Sturmian comparison theorems (even for half-linear equations), can be used as a half-linear replacement for missing transformation theory of half-linear equations, can be used to formulate **nonradial oscillation** criteria of half-linear PDE's.

